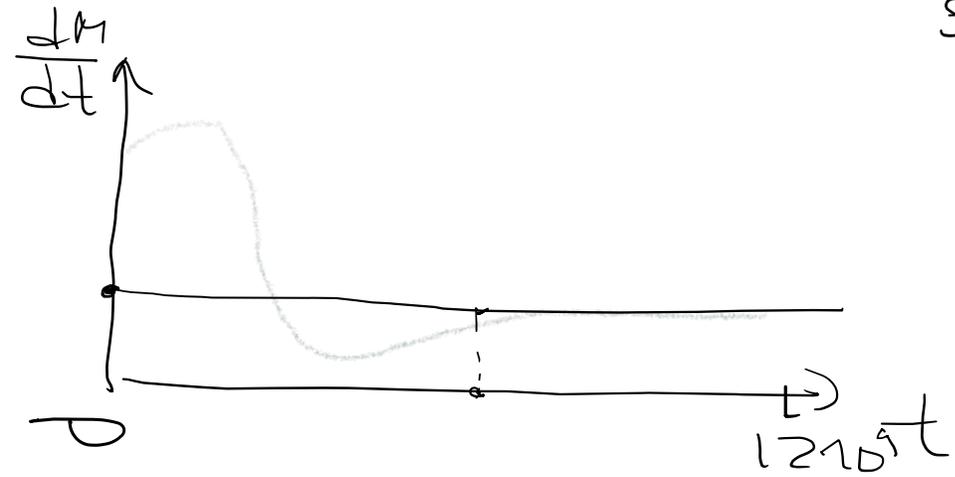




Модуль. Астрофізика.

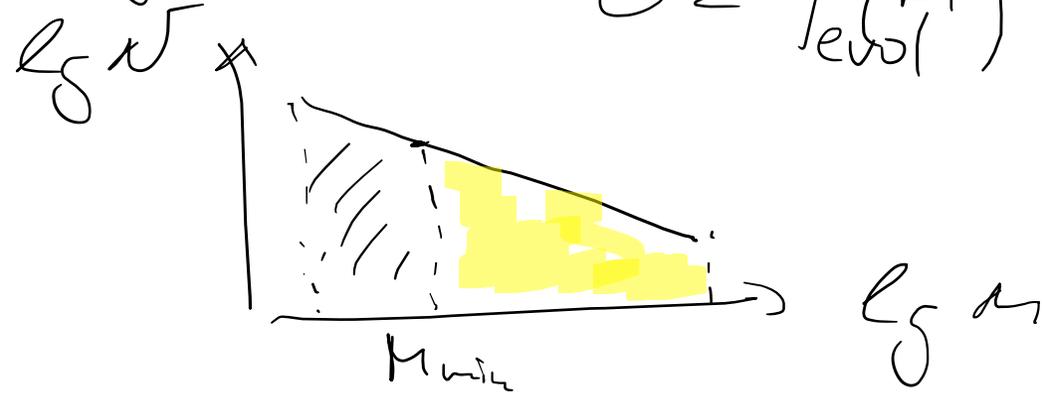
Семинар 8. (18.12)

D/3 7. a52



steady-state
 $lg M$

$$0 < f_{evol}(M) < 1, M > M_{min}$$



① Задача Халдана

$$ds^2 = c^2 dt^2 - \underbrace{a^2 dx^2}_{dr}$$

$$a = a(t)$$

$$r = ax$$

$$r = \int a dx$$

$$t = t_{obs}$$

$$r = a(t) \int dx$$

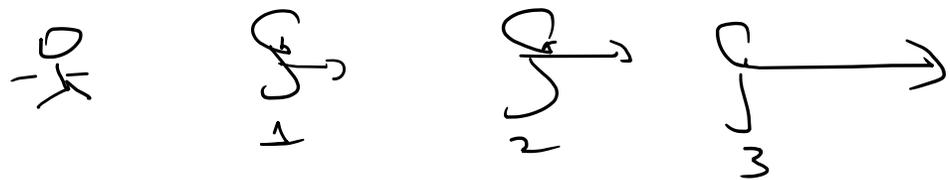
$$v = \frac{dr}{dt} = \frac{d(ax)}{dt} = \left(\frac{1}{a} \frac{da}{dt} \right) ax$$

$$= H \cdot r$$

$x = \text{const}$

$$\frac{1}{a} \frac{da}{dt} = H$$

$$\boxed{v = Hr}$$



$$v_2 = v_1 + v_{12}$$

$$v_3 = v_1 + v_{12} + v_{23}$$

$$v_3 = H \cdot r_3 = H (r_1 + r_{12} + r_{23})$$

$$v = \frac{dr}{dt} = \frac{d(ax)}{dt} = \left(x \neq \text{const} \right) = \underbrace{\dot{a}x}_{\text{ном. расм.}} + \underbrace{xa}_{\text{нерасм. глук}}$$

↑ нерасм. глук

2) Nonery tsangy Danyer?

$$d = \frac{c}{(1-\alpha)k_0} [(1+z)^t - 1]$$

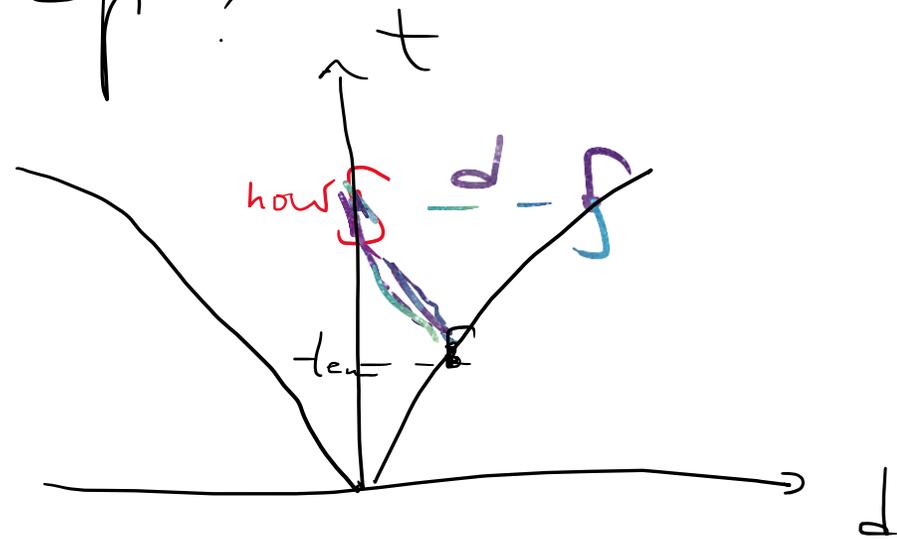
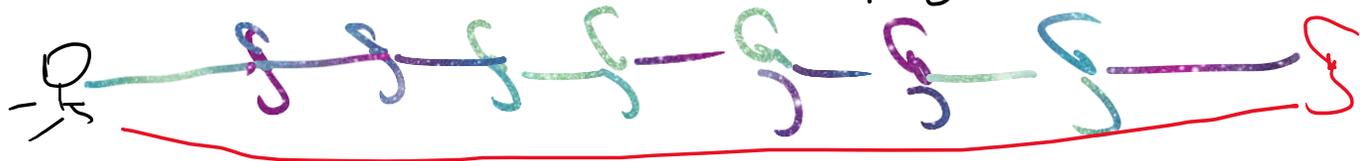
Peg Te tsangy l' d wo z

$$f(0) + \frac{f'(0)}{1!} z + \dots$$

$$d' = \frac{c}{(1-\alpha)k_0} (1-\alpha) (1+z)^t$$

$$d'(0) = \frac{c}{k_0}$$

$$d(z \approx 0) = \frac{c}{k_0} \cdot z$$



$$d(0) = 0$$

$$= \frac{c}{k_0 (1+z)^t}$$

$$d \sim z \quad \left\{ \begin{array}{l} \Rightarrow \\ \cup \sim z \\ (z \approx 0) \end{array} \right.$$

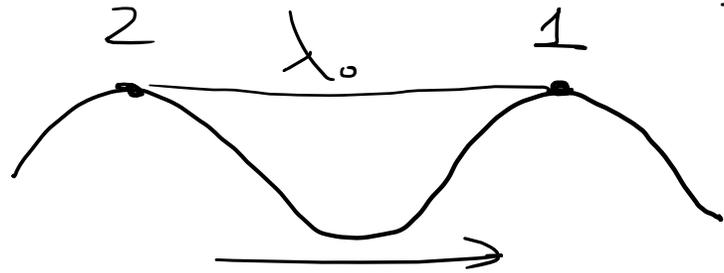
③ Kpaac. c mery. $ds^2 = c^2 dt^2 - a^2(t) dx^2$

2 re class $ds^2 = 0$

$$c^2 dt^2 = a^2(t) dx^2$$

$$dx = \frac{c dt}{a(t)}$$

$$\int_{t_{em}}^{t_{obs}} \frac{c dt}{a(t)} = \int dx = \lambda_{em}$$



$$\int_{t_{em} + t_{obs}}^{t_{obs} + t_{obs}} \frac{c dt}{a(t)} = \lambda_{em}$$

$$\frac{c t_{em}}{a(t_{em})} - \frac{c t_{obs}}{a(t_{obs})} = 0 \Rightarrow \frac{t_{em}}{t_{obs}} = \frac{a(t_{em})}{a(t_{obs})}$$

$$c t = \lambda$$

$$z+1 = \frac{a(t_{obs})}{a(t_{em})}$$

$$z \equiv \frac{t_{obs} - t_{em}}{t_{em}} = \frac{a(t_{obs})}{a(t_{em})} - 1$$

6) Сфера $X \sim \delta \delta_{\mu\nu}$

$v = H \cdot d$ $H = \dot{a}/a$

$c = H \cdot d_H$ $d_H = c/H$

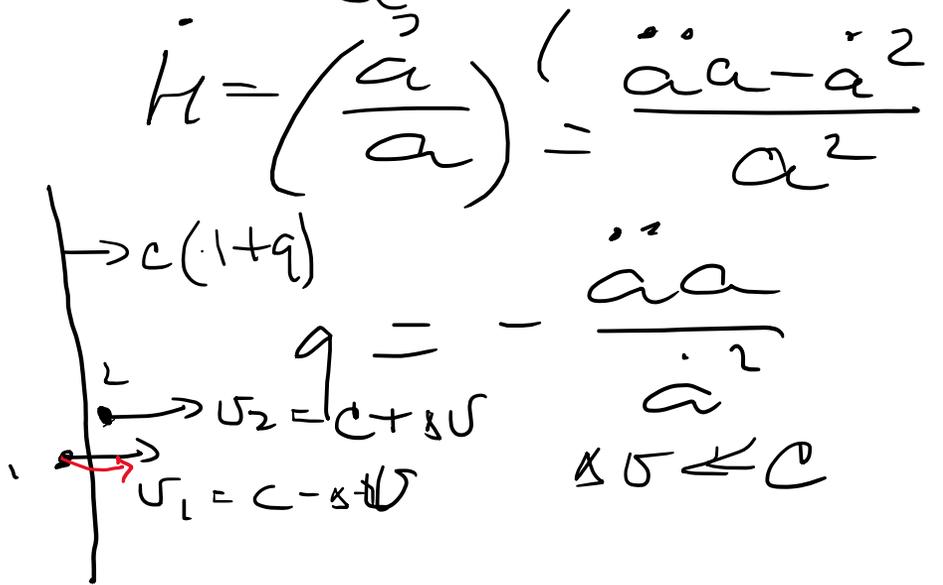
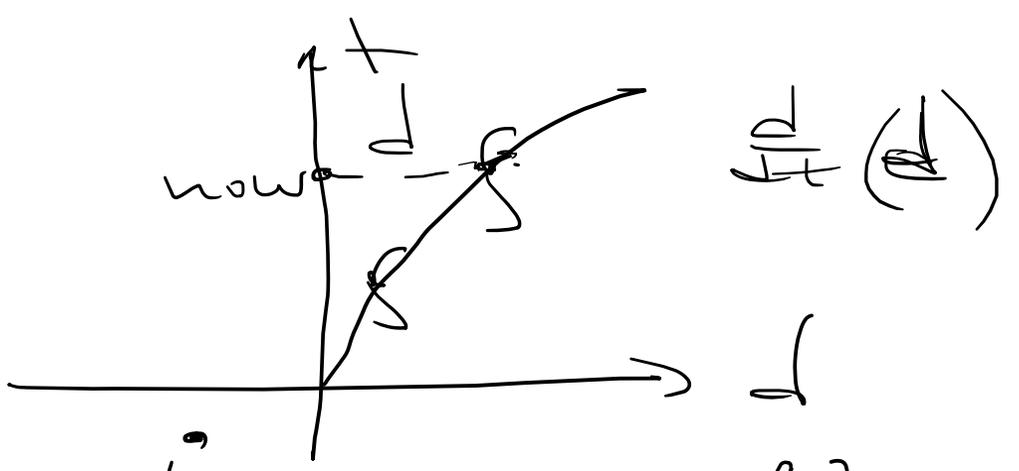
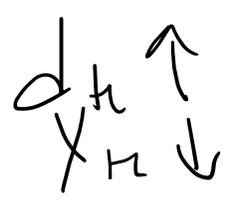
$(d_H)' = \left(\frac{c}{H}\right)' = \left(\frac{c a}{\dot{a}}\right)' = -\frac{c \dot{H}}{H^2} = \frac{\ddot{a} a - \dot{a}^2}{a^2}$

$(d_H)' = \delta_H = -c \frac{\ddot{a} a - \dot{a}^2}{a^2} \cdot \frac{a^2}{\dot{a}^2} = H = \left(\frac{\dot{a}}{a}\right) \left(\frac{\ddot{a} a - \dot{a}^2}{\dot{a}^2}\right)$

$= c \frac{\ddot{a} a - \dot{a}^2}{\dot{a}^2} = c(1+q)$

E.g. $q < 0$, so $\delta_H < c$

E.g. $q > 0$, so $\delta_H > c$



Hubble sphere $d_H c a \dot{H}$

7) Методы расчета.

$$D_{now} = a_{now} \cdot x = [a_{now} \cdot a_{em} \cdot (1+z)] = a_{em} \cdot (1+z) \cdot x =$$

\uparrow \downarrow \uparrow \downarrow
 cost. \uparrow \downarrow \uparrow \downarrow
 price. \uparrow \downarrow \uparrow \downarrow
 $D_{light} = ct = \begin{matrix} \text{to be} \\ \text{term} \end{matrix}$ \uparrow \downarrow
 \uparrow \downarrow
 $= D_{em} \cdot (1+z)$
 \uparrow
 $= \text{gross price}$
 \downarrow
 price.

$$D_{em} < D_{light} < D_{now}$$

$$V_{now} = \dot{D}_{now} = \dot{a}_{now} \cdot x$$

$$V_{em} = \dot{D}_{em} = \dot{a}_{em} \cdot x - \text{no item}$$

$$\rightarrow V_{app} = \frac{V_{em}}{(1+z)} - \text{no jobs (no price marking)}$$

$$U_e = \frac{dD_{\text{light}}}{dt} \leftarrow \text{now} \quad dD_{\text{light}} = c(d_{\text{obs}} - dt_{\text{em}})$$

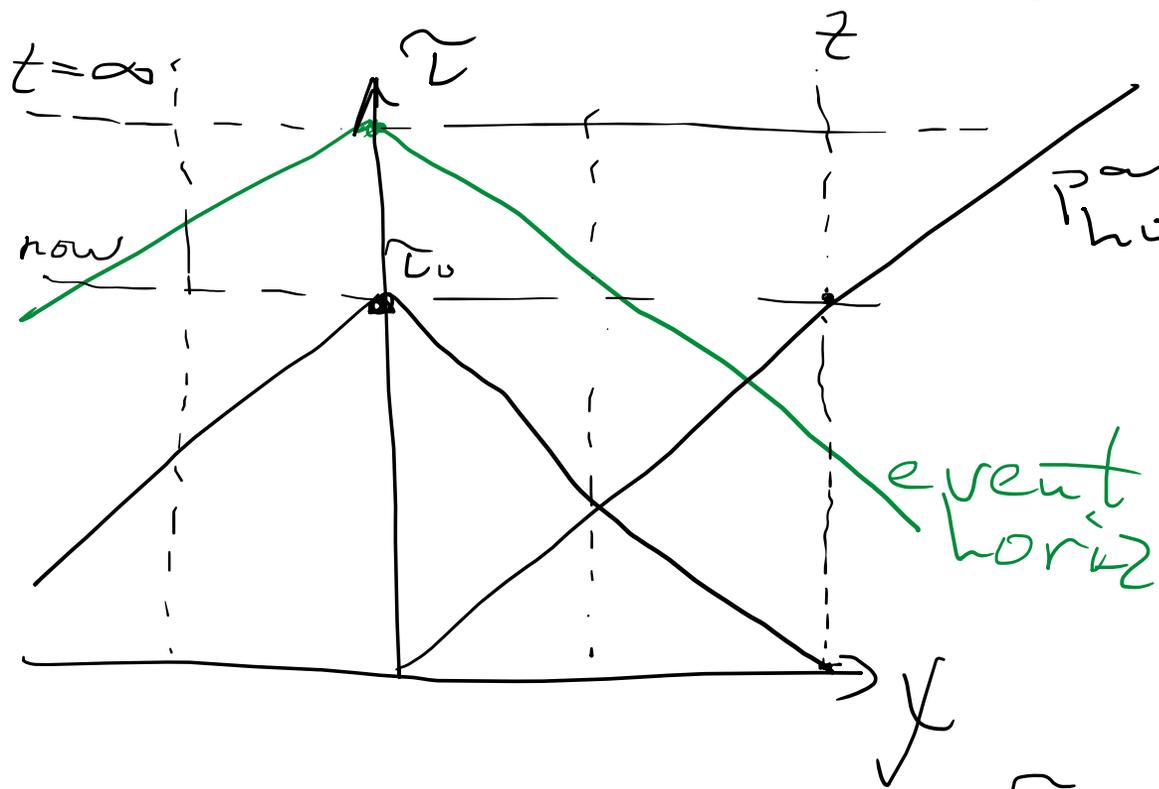
$$\frac{dD_{\text{light}}}{dt} \xrightarrow{\text{now}} = c \left[\frac{d_{\text{obs}}}{dt} - \frac{dt_{\text{em}}}{dt} \right]$$

$\frac{a_{\text{em}}}{a_{\text{obs}}} = \frac{1}{1+z}$

$$= c z \frac{dt_{\text{em}}}{dt} = c \frac{z}{z+1} < c$$

8 Conformal Penrose

$$d\tau = \frac{dt}{a(t)} \Rightarrow \underline{dx = c d\tau}$$



$$ds^2 = c^2 dt^2 - a^2 dx^2 = a^2(t) \left[\frac{c^2 d\tau^2}{a^2} - dx^2 \right]$$

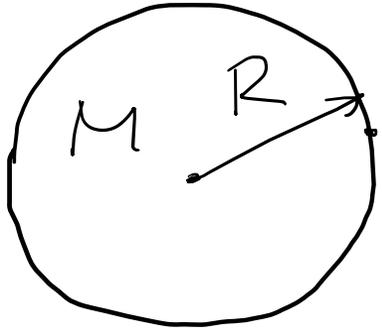
$$ds^2 = 0 \quad c dt = a dx$$

$$x_{ph} = \int_0^t \frac{c dt'}{a(t')} = c \int_0^{\text{now}} d\tau$$

$$D_{pl} = a x_{ph} = a_0 \cdot c \cdot \tau_0$$

$$\tau = \int \frac{dt}{a} = \int \frac{dt}{\frac{da}{da}} \frac{da}{a} = \int \frac{da}{a \dot{a}} = \int \frac{da}{a^2 H}$$

9 Ω
 $R = a R_0$



(3 axes, no other cap 480+)

$$\frac{1}{2} \left(\frac{dR}{dt} \right)^2 - \frac{GM}{R} = \text{const} = 0$$

$$H = \frac{1}{R} \frac{dR}{dt} \quad M = \frac{4}{3} \pi R^3 \rho$$

$$\frac{1}{2} H^2 - \frac{4}{3} \pi G \rho = 0$$

$$\rho_c = \frac{3H^2}{8\pi G}$$

$H \neq \text{const}$
 $M = M(t)$

$$\Omega = \rho / \rho_c$$



$$k = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

Ω_r
 Ω_m
 Ω_Λ
 Ω_c

$$1 = \Omega_r + \Omega_m + \Omega_\Lambda + \Omega_c$$

$$H^2 = \frac{8\pi G \rho}{3} + \frac{\Lambda c^2}{3} + \Omega_\Lambda - \left(\frac{kc^2}{a^2} \right)$$

